

Self-stabilizing, Hysteretic Boost DC-DC Converter for Portable Applications

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Motivation

- Significant dependence of converter frequency response on passive components
- Tolerances in capacitor ESR, ESL values
- Variations in inductor, capacitor values per design
- IC solution for frequency compensation required because
 - Reduction in design time
 - Reduction in part count
 - Reduction in board size, cost
 - Ease of design
- *Need to have IC solution that will give frequency compensation independent of external components*
- Various techniques in literature were studied

Comparison of Stabilizing Techniques

Characteristic	Masking LCR (and/or ESR) Parameters			RHP Zero Elimination		Adaptive control		Boundary control
	Feedforward	Modified Hysteretic	Constant LCR load	Constant capacitor discharge	Output peak control	Multiple operating point	Digital control	Voltage hysteretic control
Complexity	Medium	Low	Highest	Medium	Medium	High	High	Lowest
Response	Slowest	Fast	Medium	Medium	Slow	Slow	Slow	Fastest
Power losses	Low	Medium	Low	Highest	Low	Low	Low	Low
Output ripple	Low	Lowest	Low	Low	High	Low	Low	Low
Stable – LCR variation	Medium	Highest	High	Low	Lowest	High	High	High
Versatility	High	Low	Low	Low	Low	High	Highest	Medium

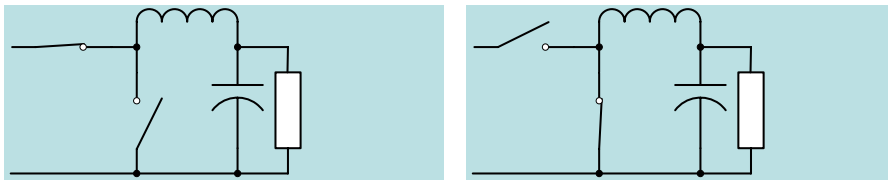
Conclusion

Hysteretic control based scheme to be extended to boost converter

Issues with Hysteretic Control in Boost Converters

Buck converter

- Inductor current ripple *in phase* with output voltage ripple –
Therefore:
 - *Current mode control*
 - *Single pole transfer function*
 - *Stable operation*



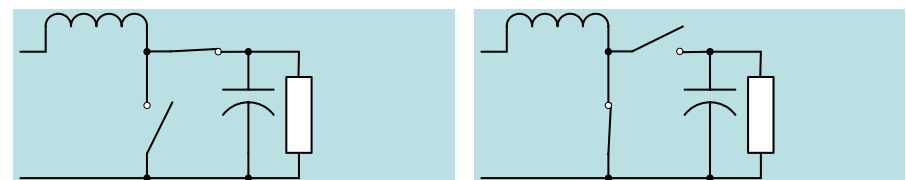
$$V_{IN} > V_{OUT} > 0$$

In steady-state, D_1 rises:- V_{OUT} rises

& S_1 on:- V_{OUT} rises

Boost converter

- Inductor current ripple *out of phase* with output voltage
Therefore:
 - *No current mode control*
 - *Double pole + RHP zero*
 - *Unstable operation*

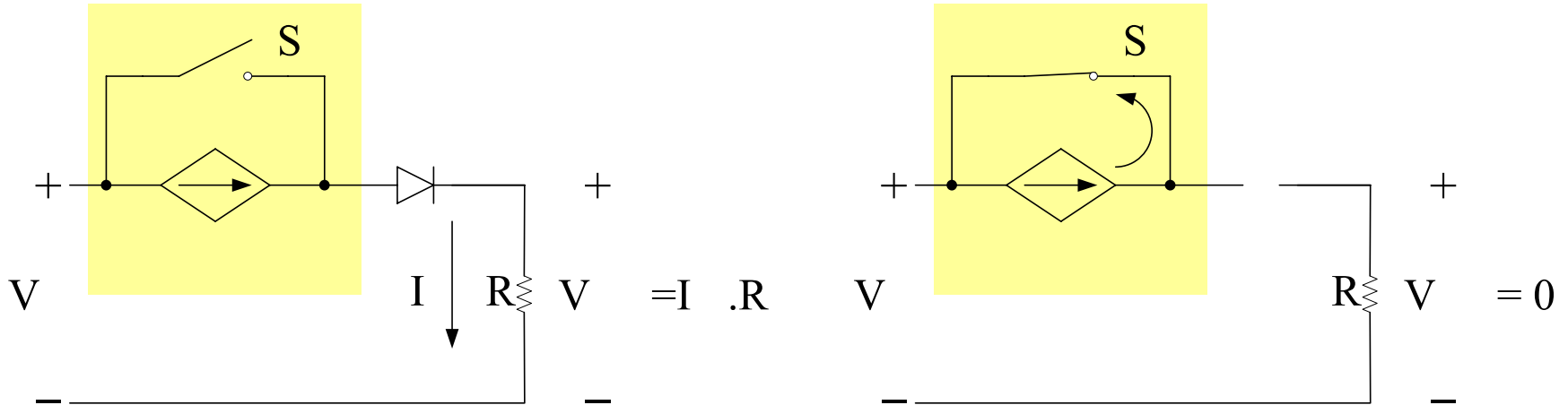


$$V_{OUT} > V_{IN} > 0$$

In steady-state, D_1 rises:- V_{OUT} rises

but S_1 on:- V_{OUT} falls

Hysteretic Control in Boost Converters: Proposed Concept



For $I_{CS} > I_{O(\text{desired})}$

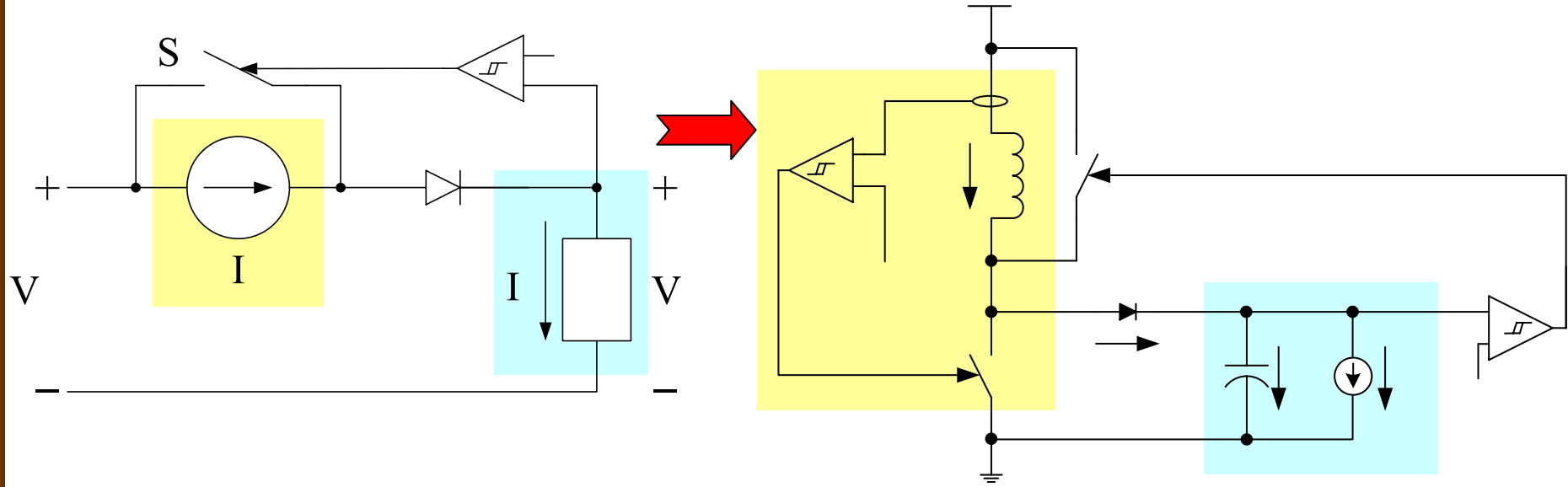
- With switch S open, $V_{\text{OUT (EQL)}} = (I_{CS})(R_{\text{OUT}}) > V_{O(\text{desired})}$
- With switch S closed, $V_{\text{OUT (EQL)}} = 0$

Now, $0 \leq V_{\text{OUT}} \leq (I_{CS})(R_{\text{OUT}})$

➤ V_{OUT} hysteretically regulated by controlling duty cycle D_A

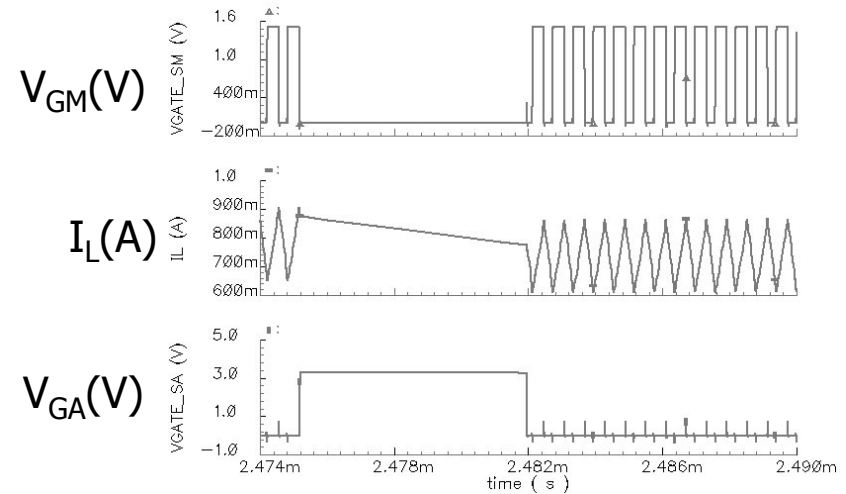
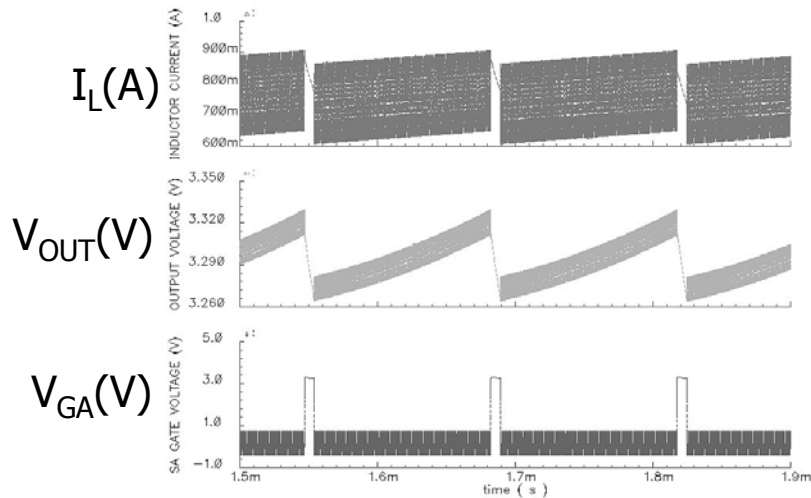
A

Hysteretic Control in Boost Converters: Implementation 1



- Fixed $I_{REF} \geq I_{LMIN} = I_{OMAX}/(1-D_M)$
- ✓ Very fast transient response
- ✓ Stable operation without frequency compensation circuits
- × Poor efficiency especially at light loads

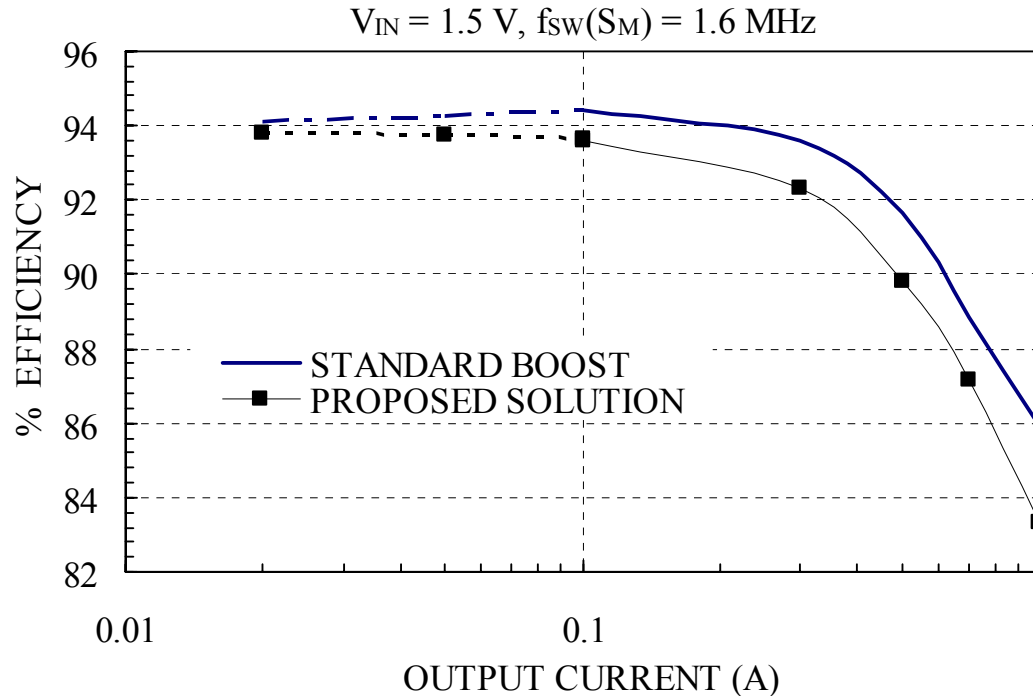
Steady-state Simulations



Specs: $V_{IN} = 1.5 \text{ V}$, $V_{OUT} = 3.3 \text{ V} \pm 5\%$, $I_{OUT} = 0.1 - 1 \text{ A}$

- I_L free-wheels during on-time of switch S_A
- Switching f_{SW} of $S_A \ll f_{SW}$ of S_M
- Steady-state duty cycle $D_A \sim 5\%$
- ✓ $V_{OUT} = 3.3 \text{ V} \pm 35\text{mV}$

Simulated Power Efficiency



- Proposed solution has slightly lower efficiency (up to 2 % @ 1 A) compared to standard boost converter
- ✓ At light loads, the efficiencies are comparable
- ✓ At $\sim 20 \text{ mA}$ load, the efficiencies equal each other

Summary

- Techniques to **ease stability requirements** in DC-DC converters reviewed
- **Hysteretic control** in buck converters fastest, simple and **w/o compensation**
- Voltage-mode hysteretic control not been used so far in boost converters
- Novel technique presented to implement **hysteretic control in boost converters**
- Proposed method can be used with good regulation ($3.3\text{ V} \pm 5\%$) and fast transient response without using any compensation circuit
- Efficiency degraded up to 2 % @ 1 A, but < 1% at light loads
- Solution can be used towards an **increased degree of integration** in DC-DC converters – **without an external frequency compensation circuit**