

# Integrated Low Voltage, Power Efficient DC-DC Converters for Dynamic Power Supplies of Power Amplifiers

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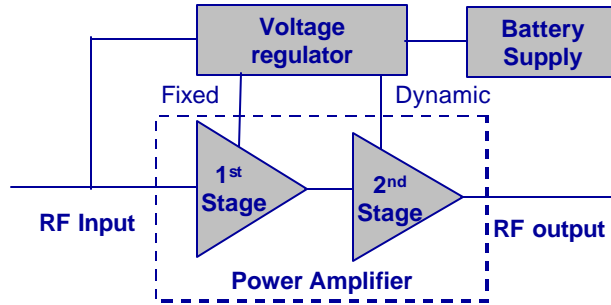
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## Abstract

- **Power Amplifiers**
  - Consume majority of power in radio transceivers
  - Maximum efficiency when output signal is rail-to-rail
  - ⇒ Dynamic power supply for the PA depending on signal strength
  - ⇒ High efficiency voltage regulators
- **DC-DC Converters**
  - High efficiency compared to linear regulators
  - Dynamic control loop for selection of supply voltage
  - Efficient and stable control of high speed converters
- **Implementation**
  - SiGe BiCMOS process technology
  - Prototype: Converter and PA separately
  - Goal: High efficiency linear integrated PA

## Objective

- Power Amplifiers are “long pole” in the tent
  - Cost, reliability and battery life



- Variable supply voltage to the PA on demand
  - Optimum efficiency, improves battery life

## Why Switching Regulators?

- Linear regulators
  - Simple, low cost
  - Poor efficiency

$$\eta = \frac{P_{out}}{P_{out} + P_{reg}}$$

- Switching regulators
  - Complex, costlier
  - High efficiency (80-95%)
  - Noisy

## PA as a Load for Converter

$V_{DD} = 0.4 - 2.5 V$

$I_{load} = 0 - 1 A$

$L (nH)$

$R_c + V_{CEQ}/I_{CQ}$

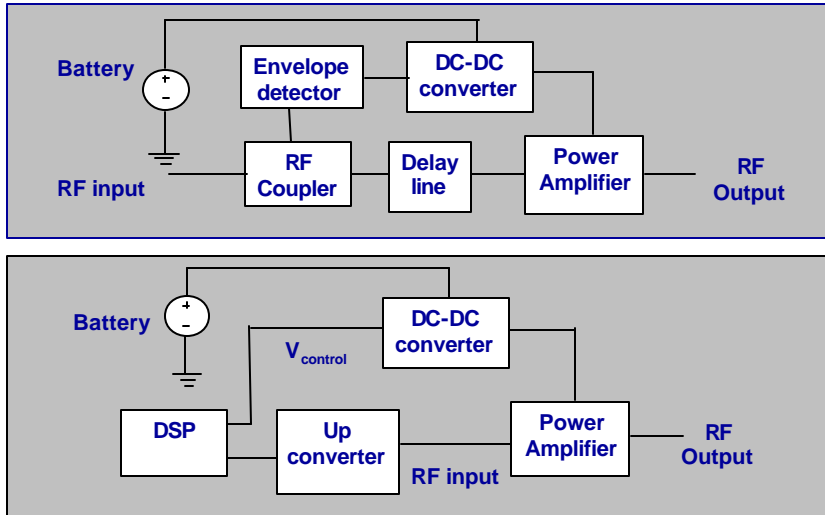
**CDMA-IS 95 requirements**

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## Functional Block Diagram

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## Supply Selection Schemes



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## DC-DC controllers

| Control mode                | Voltage | Peak-I | Average-I | Hysteretic |
|-----------------------------|---------|--------|-----------|------------|
| $V_{out}$ -ripple           | Worst   | Worst  | Worst     | Best       |
| D-limit                     | Poor    | Poor   | Poor      | Best       |
| Frequency                   | Best    | Best   | Best      | Poor       |
| Complexity                  | Good    | Poor   | Poor      | Best       |
| Compensation                | Worst   | Good   | Poor      | Best       |
| $V_{in}$ - $t_{response}$   | Worst   | Worst  | Good      | Best       |
| $I_{load}$ - $t_{response}$ | Worst   | Worst  | Worst     | Best       |

**Source:** G. A. Rincon-Mora, "Self-oscillating hysteretic V-mode controllers: From the ground up," 2001 Power Electronics Specialist Conference.

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## Design Considerations

- |  |   |
|--|---|
| <ul style="list-style-type: none"> <li>▪ <b>High efficiency over wide loading conditions</b> <ul style="list-style-type: none"> <li>▪ Conduction loss at heavy load</li> <li>▪ Switching loss at low load</li> </ul> </li> <li>▪ <b>Dynamic voltage adjustment</b> <ul style="list-style-type: none"> <li>▪ 0.4 V to 2.5 V on demand</li> </ul> </li> <li>▪ <b>Fast response, output slew rate</b> <ul style="list-style-type: none"> <li>▪ <math>V_{ref}</math> variation at 1.22 MHz</li> <li>▪ Power adjustment of 1 dB in 666 <math>\mu</math>sec as directed by the base station</li> </ul> </li> </ul> | <ul style="list-style-type: none"> <li>▪ <b>Stability over duty cycle range</b> <ul style="list-style-type: none"> <li>▪ Duty cycle variation: 16% to 100%</li> </ul> </li> <li>▪ <b>Switching frequency</b> <ul style="list-style-type: none"> <li>▪ Smaller external components at higher frequency</li> <li>▪ Higher switching loss</li> </ul> </li> <li>▪ <b>Noise</b> <ul style="list-style-type: none"> <li>▪ Switching noise</li> <li>▪ Substrate coupling</li> </ul> </li> <li>▪ <b>Layout</b></li> </ul> |
|--|---|

## Work Plan

- | Activity   | Status               |
|--|----------------------|
| <ul style="list-style-type: none"> <li>▪ Specifications</li> <li>▪ Design of prototype converter</li> <li>▪ Evaluation of prototype</li> <li>▪ Design of Integrated PA</li> <li>▪ Evaluation of integrated PA</li> </ul> | <p>: In progress</p> |