

# Harvesting Kinetic Energy with Switched-Inductor DC–DC Converters

Dongwon Kwon, Gabriel A. Rincón-Mora, and Erick O. Torres

Georgia Tech Analog, Power, and Energy IC Research  
 {dkwon3, rincon-mora, erick.torres}@gatech.edu

**Abstract**—The potential application space for miniaturized systems like wireless microsensors is expansive, from reconnaissance mission work and remote sensors to biomedical implants and disposable consumer products. Conforming to microscale dimensions, however, constrains energy and power to such an extent that sustaining critical power-hungry functions like wireless communication is next to impossible. Harvesting ambient energy offers an appealing alternative, except the act of transferring energy requires power that could easily exceed what the transducer generates in the first place. This paper presents how to design low-power switched-inductor converters capable of producing net energy gains when supplied from low-power piezoelectric and electrostatic kinetic-harvesting sources.

## I. HARVESTING KINETIC ENERGY IN VIBRATIONS

Wireless microsensors can enjoy popularity in, for example, medical treatment [1] and monitoring tire pressure [2] because they offer *in-situ*, real-time, non-intrusive processing capabilities, in other words, because they add intelligence in little to negligible space. The problem is a miniaturized platform necessarily constrains the energy capacity (i.e., operational life) of an on-board battery to impractical levels [3]. Energy harvesting is therefore an attractive alternative, as it continuously replenishes a battery from ambient energy in light, temperature, and/or motion. Of these, solar light produces the highest output power density, except when supplied from indoor lighting under which conditions power decreases drastically [4]. Harnessing thermal energy is viable [5], but microscale dimensions severely limit temperature gradients, the fundamental source from which the device draws energy [3]. Harvesting the kinetic energy in motion may not compete with solar power but, in contrast to indoor lighting and thermal sources, moderate and consistent output power across a vast range of applications is typical [3]–[4].

Although the application ultimately determines which kinetic energy harvesting scheme is optimal, piezoelectric transducers, harvester circuits for which Section II describes, are relatively mature and produce comparatively higher power. On-chip piezoelectric devices, however, are far from mature, which is where electrostatic harvesters (discussed in Section III) find an edge, because microelectromechanical systems (MEMS) technologies can more aptly integrate variable, parallel-plate capacitors on chip [3]–[4]. Magnetic schemes, unfortunately, suffer from low output voltages [3], which practical circuits cannot easily accommodate without sacrificing some, if not all, the energy harvested.

## II. PIEZOELECTRIC HARVESTERS

When a mechanical vibration stimulates a piezoelectric material, the internal charge configuration changes to generate

a voltage across the surfaces [3]–[4]; in other words, an ac current charges and discharges the capacitance between the surfaces [6]. The purpose of a piezoelectric harvester is to transfer the energy in the form of charge to an intermediate reservoir, such as a capacitor or battery. The harvester does not supply the load directly because the mechanical input is unpredictable and therefore unreliable for on-demand loading events [7]. Considering its aim, the system must therefore condition and rectify an ac source into a dc output without losing considerable energy, which is why efficient rectifiers [8]–[10] and rectifiers with the conditioned input and output voltages that produce higher power [6], [11]–[12] are the subject of ongoing research.

### A. Rectifier-Free, Switched-Inductor System

While the efficiency of rectifiers can be high, the power they draw is not because the rectifier only transfers energy when the input voltage exceeds its output. In other words, the rectifier can only harvest for a fraction of the vibration cycle, when the piezoelectric cantilever bends enough to generate a voltage that surpasses the rectified output. To circumvent this fundamental limitation, the harvester, as shown in Fig. 1 [7], [13], can temporarily store the transduced energy in an inductor before delivering it to the storage capacitor or battery.

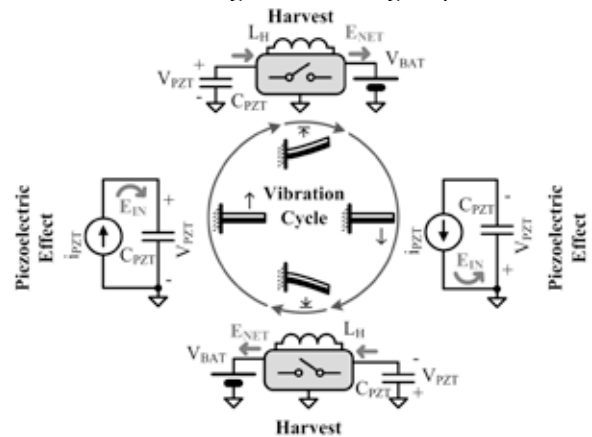


Fig. 1. Rectifier-free, switched-inductor piezoelectric harvesting cycle.

The rectifier-free, switched-inductor harvester in Fig. 1 first allows the half of the vibration to induce the transducer to source current  $i_{PZT}$  into piezoelectric capacitance  $C_{PZT}$ . Once  $C_{PZT}$ 's voltage reaches its peak, which corresponds to the transducer's maximum displacement point, the system transfers  $C_{PZT}$ 's stored energy into harvesting inductor  $L_H$ , after which point the circuit reconfigures its switches to de-energize  $L_H$  into the battery. Because energizing and delivering  $L_H$ 's energy to the battery only requires a few  $\mu$ s and the vibration period is on the order of ms, the position of

the cantilever practically remains unchanged through this  $L_H$ 's entire energy-transfer process. Similarly, after the other half of the vibration cycle induces the transducer to maximally charge  $C_{PZT}$  in the other direction, the harvester discharges  $C_{PZT}$  into  $L_H$  and then redirects  $L_H$ 's energy into the battery.

$C_{PZT}$  stores the electrical energy produced by the piezoelectric effect each half cycle, so input energy per cycle  $E_{IN}$  is

$$E_{IN} = \frac{1}{2} C_{PZT} V_{PZT(PEAK+)}^2 + \frac{1}{2} C_{PZT} V_{PZT(PEAK-)}^2, \quad (1)$$

where  $v_{PZT(PEAK+)}$  and  $v_{PZT(PEAK-)}$  are  $C_{PZT}$ 's positive and negative peak voltages, respectively. Without the harvester, the quarter of the vibration cycle after the positive and negative peak points would be used to discharge  $C_{PZT}$  from their respective peaks. In contrast, since the harvester extracts all the stored energy in  $C_{PZT}$  and resets the voltage to zero at the peaks, the whole vibration cycle is exploited to generate the higher peak voltages compared to the open-circuited counterparts, the maximum input voltage a rectifier-based system can experience. Higher peak voltages thus indicate the harvester draws more energy from the environment.

The driving force behind adopting a switched-inductor topology is  $L_H$  and its accompanying switches, which conduct with close to zero voltages across them, dissipate little power. Unfortunately, harvested power can also be low, so parasitic energy losses  $E_{LOSSES}$  in  $L_H$ 's equivalent series resistance (ESR), the switches' turn-on resistances, driving parasitic capacitance of switches, and controller quiescent current  $I_Q$  can use a considerable fraction of the energy harvested:

$$E_{LOSSES} = R_{EQ+} I_{L(PEAK+)}^2 T_{C+} + R_{EQ-} I_{L(PEAK-)}^2 T_{C-} + C_{EQ} V_{BAT}^2 + I_Q V_{BAT} T_{VIB}, \quad (2)$$

where  $R_{EQ+/-}$  represent the equivalent resistances that conduct peak inductor current  $I_{L(PEAK+/-)}$  during conduction time  $T_{C+/-}$  for positive and negative half cycles, and  $C_{EQ}$  is the total equivalent parasitic capacitance present that must be charged to and discharged from battery voltage  $V_{BAT}$  during the vibration period  $T_{VIB}$  [7]. Thus, the net energy harvested  $E_{NET}$  is necessarily below the energy the transducer avails ( $E_{IN}$ ):

$$E_{NET} = E_{IN} - E_{LOSSES}. \quad (3)$$

### B. Circuit Embodiment

In the circuit shown in Fig. 2, for example, after  $i_{PZT}$  charges  $C_{PZT}$  across half the vibration cycle to its positive peak voltage, switches  $S_1$  and  $S_N$  first energize  $L_H$ , and  $S_1$  and diode-switch  $D_N$  then steer  $L_H$ 's current  $i_L$  into  $V_{BAT}$ . Similarly, after  $i_{PZT}$ 's negative phase charges  $C_{PZT}$  to its negative peak voltage,  $S_1$  and  $S_N$  again energize  $L_H$  but now  $S_N$  and  $D_I$  channel  $i_L$  into  $V_{BAT}$ . Notice asynchronous diodes  $D_N$  and  $D_I$  stop conducting when the system depletes  $L_H$ : when  $i_L$  attempts to reverse.

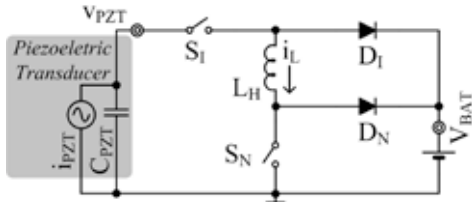


Fig. 2. A rectifier-free switched-inductor piezoelectric power stage.

Since  $L_H$  energizes as soon as its terminal voltages surpass zero Volts, the converter avoids the input threshold voltage normally imposed by rectifier-based systems, whose

piezoelectric input voltages must exceed their rectified outputs. Additionally, by inverting  $L_H$ 's output conduction path (between  $D_N$  and  $D_I$ ), the system harnesses energy during the positive and negative vibration cycle, effectively "full-wave rectifying" the ac input without a rectifier circuit.

From a time-domain perspective, piezoelectric voltage  $v_{PZT}$  rises (as  $C_{PZT}$  charges) through the positive half cycle, as Fig. 3a illustrates from approximately 10.7 to 15.7 ms. When  $v_{PZT}$  peaks at 15.7 ms,  $S_1$ - $L_H$ - $S_N$  discharge  $C_{PZT}$  to ground abruptly. During this quick discharge,  $S_1$ - $S_N$  first energizes  $L_H$  in 10  $\mu$ s, as Fig. 3b shows, and  $S_1$ - $D_N$  then depletes  $L_H$  into  $V_{BAT}$  in 1  $\mu$ s. Similarly,  $v_{PZT}$  falls in the negative half cycle from 15.7 to 20.7 ms and  $S_1$ - $S_N$  energizes  $L_H$  in 10  $\mu$ s and  $S_N$ - $D_I$  drains  $L_H$  in 1  $\mu$ s. The fact  $L_H$  de-energizes means  $i_L$  flows into  $V_{BAT}$ , which is to say the harvester harnesses energy, as the gray rising staircase energy trace  $E_{NET}$  in Fig. 3a corroborates.

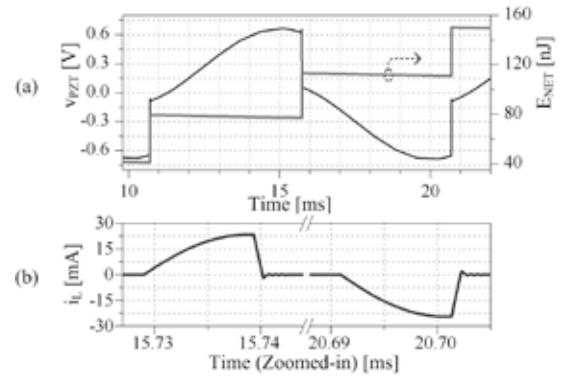


Fig. 3. Simulated waveforms of the piezoelectric harvester.

### C. Synchronization and Control

For the system to harvest, it must drain  $C_{PZT}$ 's energy into  $L_H$  when vibrations maximally charge  $C_{PZT}$ . Comparator  $CP_{PK}$  in Fig. 4 therefore detects when  $v_{PZT}$  peaks by comparing  $v_{PZT}$  to its delayed counterpart  $v_D$ . Since  $v_{PZT}$  leads  $v_D$ , the moment  $v_{PZT}$  falls below  $v_D$  (and  $CP_{PK}$  trips) indicates  $v_{PZT}$  reached its positive peak. Similarly,  $v_{PZT}$  rising above  $v_D$  implies  $v_{PZT}$  just reached its negative peak. Although  $CP_{PK}$  functions continuously, its low bandwidth requirement allows it to operate in subthreshold (with low power).

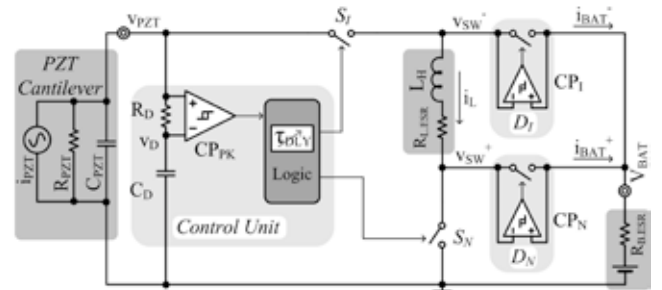


Fig. 4. Switched-inductor piezoelectric harvester circuit.

The system must also detect when to stop energizing  $L_H$ . To this end, because  $C_{PZT}$  transfers energy to  $L_H$  in a quarter of its resonance period, the controller estimates  $L_H$ 's energizing time by tuning adjustable delay  $\tau_{DLY}$  in Fig. 4 to  $\sqrt{C_{PZT} L_H}$ . Note comparator-controlled switches  $D_I$  and  $D_N$  implement diodes by conducting current  $i_{BAT}$  into  $V_{BAT}$  only when switching signals  $v_{SW}^+$  and  $v_{SW}^-$  surpass  $V_{BAT}$ . The power a conventional diode would otherwise dissipate can exceed the

conduction loss across a MOS switch plus the quiescent power through its controlling comparator, which the system only powers on demand, when  $v_{SW}^+$  and  $v_{SW}^-$  surpass  $V_{BAT}$ .

### III. ELECTROSTATIC HARVESTERS

A motion-sensitive, parallel-plate variable capacitor ( $C_{VAR}$ ) draws kinetic ambient energy by dampening vibration forces [3]. More specifically, as motion separates  $C_{VAR}$ 's plates, capacitance decreases and either  $C_{VAR}$ 's voltage  $v_C$  increases (because  $q_C$  equals  $C_{VAR}v_C$ ) to increase its stored energy  $E_C$  to  $C_{VAR}(V_{Final} - V_{Initial})^2$  or charge  $q_C$  decreases (i.e.,  $C_{VAR}$  releases  $q_C$ ) to generate current  $i_{HARV}$  as  $\Delta q_C/dt$ . The challenge with keeping  $q_C$  constant to augment  $E_C$  is that  $v_C$  can reach levels (e.g., 100 – 300 V) well above the breakdown voltages of high-volume, low-cost semiconductor technologies (e.g., 5 V). Although constraining voltage harvests less energy (at a linear rate, as opposed to the parabolic rise  $E_C$  enjoys in the former case),  $\Delta q_C$  generates power in the more benign form of current:

$$P_C = V_{CONST} i_{HARV} = V_{CONST} \frac{dq_C}{dt} = V_{CONST} \frac{d(C_{VAR} v_C)}{dt} = V_{CONST}^2 \frac{dC_{VAR}}{dt}. \quad (4)$$

#### A. Battery-Constrained and -Directed System

Constraining  $v_C$  to a system-generated or intermediate source is possible [14] but fixing  $v_C$  to  $V_{BAT}$  by connecting  $C_{VAR}$  to  $V_{BAT}$  is more efficient because  $C_{VAR}$  channels  $i_{HARV}$  directly into  $V_{BAT}$  [15]–[16]. Since  $C_{VAR}$  generates  $q_C$  when  $C_{VAR}$  decreases, the system must first precharge  $C_{VAR}$  to  $V_{BAT}$  when  $C_{VAR}$  peaks at  $C_{MAX}$ , as Fig. 5 illustrates. Energizing  $C_{VAR}$ , however, represents an energy investment  $E_{INV}$  from  $V_{BAT}$ :

$$E_{INV} = \frac{1}{2} C_{MAX} V_{BAT}^2. \quad (5)$$

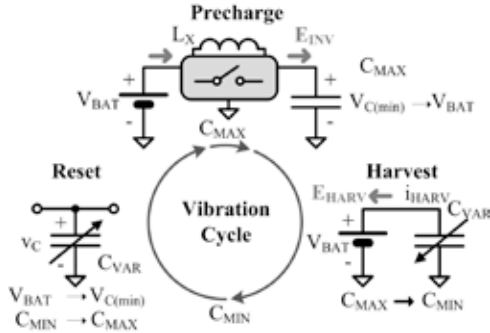


Fig. 5. Battery-constrained and -directed electrostatic harvesting cycle.

The energy harvested  $E_{HARV}$  when subsequently connecting  $C_{VAR}$  to  $V_{BAT}$  and vibrations decrease  $C_{VAR}$  to minimum  $C_{MIN}$  must exceed  $E_{INV}$  and whatever other losses  $E_{LOSSES}$  exist for the system to produce a net gain  $E_{NET}$ :

$$E_{HARV} = \int V_{BAT} i_{HARV}(t) dt = \Delta C_{VAR} V_{BAT}^2 \quad (6)$$

and

$$E_{NET} = E_{HARV} - E_{INV} - E_{LOSSES} = (0.5C_{MAX} - C_{MIN})V_{BAT}^2 - E_{LOSSES}, \quad (7)$$

where  $\Delta C_{VAR}$  is  $C_{MAX} - C_{MIN}$ . To harvest in the next vibration cycle, the system must detach  $C_{VAR}$  from  $V_{BAT}$  at  $C_{MIN}$  (to avoid reverse current from otherwise discharging  $V_{BAT}$ ) and wait for vibrations to pull  $C_{VAR}$ 's plates together until  $C_{VAR}$  peaks at  $C_{MAX}$ , prompting the system to repeat the sequence.

#### B. Switched-Inductor Circuit Embodiment

Before attaching  $C_{VAR}$  to  $V_{BAT}$ , the system must precharge  $C_{VAR}$  to  $V_{BAT}$  with little to negligible losses, because charging

$C_{VAR}$  directly from  $V_{BAT}$  through a switch dissipates considerable power with respect to the little energy  $C_{VAR}$  induces. As in the piezoelectric case, the switched-inductor harvester in Fig. 6 dissipates little power because energy-transfer inductor  $L_X$  and the switches, which conduct with close to zero Volts across them, are nearly lossless. Functionally,  $S_E$  energizes  $L_X$  from  $V_{BAT}$  before disengaging and allowing  $S_D$  to deplete  $L_X$  into  $C_{VAR}$ . Note this precharge phase only lasts a small fraction of the vibration cycle so  $C_{VAR}$  remains virtually constant at around  $C_{MAX}$  through this phase.

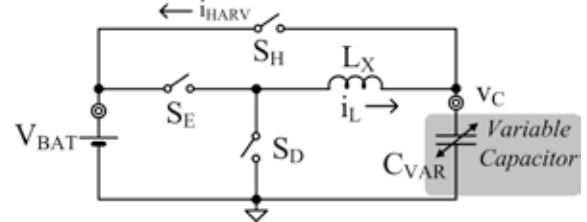


Fig. 6. A switched-inductor, voltage-constrained electrostatic power stage.

After precharging  $C_{VAR}$ , the system disengages  $S_D$  and connects  $C_{VAR}$  to  $V_{BAT}$  with  $S_H$  to start the harvesting phase. Therefore, as vibrations decrease  $C_{VAR}$  from 391 pF to 100 pF, for example, as Fig. 7 shows between 23.7 and 24.05 ms,  $i_{HARV}$  flows into a 3.5-V battery. The energy the battery accumulates in one cycle is sufficiently high to overcome its initial investment  $E_{INV}$  (-2.75nJ in Fig. 7) and the system's parasitic losses  $E_{LOSSES}$  with a net gain, in this case, of 1 nJ per cycle.

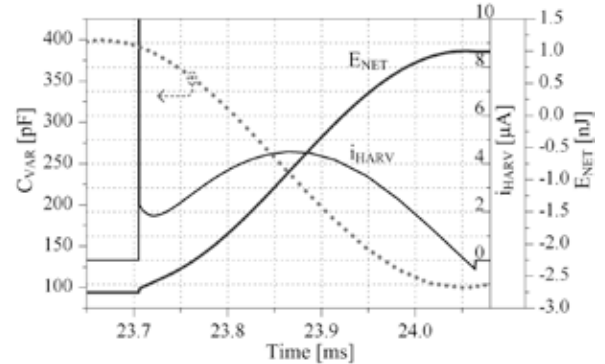


Fig. 7. Simulated waveforms of the electrostatic harvester during the harvesting phase.

#### C. Synchronization and Control

Notice the harvester must monitor  $C_{VAR}$  to precharge and subsequently connect it to  $V_{BAT}$  at  $C_{MAX}$ . Fortunately, in the reset phase, because  $C_{VAR}$  floats when it rises to  $C_{MAX}$  and its voltage  $v_C$  therefore decreases proportionately (since  $Q_{CONST}$  is  $C_{VAR}v_C$ ), sensing when  $v_C$  reaches its minimum voltage indicates when  $C_{VAR}$  peaks. To this end, as in the piezoelectric case, comparator  $CP_{P-STRT}$  in Fig. 8 senses when  $v_C$ , which leads its delayed counterpart  $v_D$ , begins to rise above  $v_D$ , prompting the logic to start the precharge phase.

Similar to the piezoelectric case, the system must also determine how long to energize  $L_X$  to precharge  $C_{VAR}$  to  $V_{BAT}$ . Consider that undercharging  $C_{VAR}$  means  $S_H$  will first charge  $C_{VAR}$  to  $V_{BAT}$  inefficiently at the beginning of the harvesting phase, decreasing the net energy gain of the system. Unfortunately, overcharging  $C_{VAR}$  likewise represents a loss

because  $S_H$  discharges  $C_{VAR}$  to  $V_{BAT}$  inefficiently, again, at the beginning of the harvesting phase. Hence, the harvester must tune  $L_X$ 's energizing time to precisely precharge  $v_C$  to  $V_{BAT}$  by adjusting delay  $\tau_{DLY}$  in Fig. 8. Afterwards,  $CP_{P-END}$  detects the end of precharging when  $L_X$  depletes (i.e.,  $i_L=0$ ) by comparing the switching node voltage  $v_{SW}$  to 0 V, and prompt the harvesting phase to begin by setting  $S_H$ 's S-R latch.

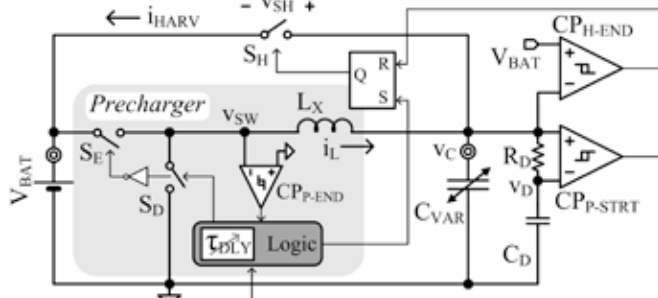


Fig. 8. Switched-inductor, voltage-constrained electrostatic harvester circuit.

In the harvesting phase,  $i_{HARV}$  induces a voltage drop across  $S_H$ 's turn-on resistance that raises  $v_C$  slightly above  $V_{BAT}$  (by  $v_{SH}$ ), keeping  $CP_{H-END}$ 's output from resetting  $S_H$ 's S-R latch. Once  $C_{VAR}$  reaches  $C_{MIN}$  and  $i_{HARV}$  consequently falls to zero,  $v_C$  drops to  $V_{BAT}$  and  $CP_{H-END}$  trips, resetting the latch and disengaging  $S_H$ , all of which marks the end of the harvesting phase. Note  $CP_{P-START}$ ,  $CP_{P-END}$ , and  $CP_{H-END}$  only operate during their respective phases to conserve energy. Additionally, because the vibration frequency is typically low, the vibration sensing comparators  $CP_{P-START}$  and  $CP_{H-END}$  have low bandwidth requirements and are allowed to function properly in subthreshold, with nA's of current.

#### IV. DISCUSSION

Although the switched-inductor circuits of Figs. 4 and 8 illustrate practical piezoelectric and voltage-constrained electrostatic harvesters, they do not represent all possible embodiments of the same. Manually tuning the energizing time of the inductor, for instance, is not the only means of determining when to stop energizing. A correcting loop that adjusts the delay from cycle to cycle and operates only a fraction of each cycle could also adjust the time, albeit at the cost of additional power losses. Perhaps a more fundamental point to highlight is the significance of producing a net energy gain with these harvesters, even if only a few nJ per cycle. The truth is the power these harvesters generate when constrained to miniaturized platforms is not sufficient to power practical applications like wireless microsensors. Generating power, however, is not as important as accumulating energy because sensors, for the most part, need not operate continuously. In other words, intermediate batteries can supply the power that sensors momentarily require when charged (over time) by these harvesters.

#### V. CONCLUSIONS

The fundamental challenge in harvesting ambient energy with microscale devices is producing a net energy gain, that is to say, conditioning and transferring energy and synchronizing the system to vibrations without dissipating considerable power in the process. Reducing losses is the driving force behind the adoption of switched-inductor circuits, because

inductors and switches that conduct while dropping nearly zero Volts are quasi-lossless. One problem is inductors are bulky and difficult to integrate, which is why using only one inductor is so important. Still, small-scale transducers generate little power, losing a considerable portion to otherwise negligible conduction, switching, and quiescent losses and achieving efficiencies of 40-70%, even if functional blocks operate only a fraction of the vibration period with nA's of current [7], [13]. Nevertheless, continuously producing a net output power of even a few  $\mu W$ 's can charge a battery so that, when a sensor needs energy, which does not typically happen often, the battery can readily supply it. The idea is to supplement the system with enough energy over time to extend its operational life and avoid having to replace an otherwise easily exhaustible battery.

#### REFERENCES

- [1] D.A. La Van, T. McGuire, and R. Langer, "Small-scale systems for in vivo drug delivery," *Nature Biotechnology*, vol. 21, no. 10, pp. 1184-1191, Oct. 2003.
- [2] M.D. Seeman, S.R. Sanders, and J.M. Rabaey, "An ultra-low-power management IC for energy-scavenged wireless sensor nodes," *IEEE Power Electronics Specialists Conf.*, pp. 925-931, June 2008.
- [3] P.D. Mitcheson, E.M. Yeatman, G.K. Rao, A.S. Holmes, and T.C.Green, "Energy harvesting from human and machine motion for wireless electronic devices," *Proceedings of the IEEE*, vol. 96, no. 9, pp. 1457-1486, Sept. 2008.
- [4] S. Roundy, P.K. Wright, and J.M. Rabaey, *Energy Scavenging for Wireless Sensor Networks with Special Focus on Vibrations*, 1<sup>st</sup> ed., Massachusetts: Kluwer Academic Publishers, 2004.
- [5] H. Lhermet, C. Condemine, M. Plissonnier, R. Salot, P. Audebert, and M. Rosset, "Efficient power management circuit: from thermal energy harvesting to above-IC microbattery energy storage," *IEEE J. Solid-State Circuits*, vol. 43, no. 1, pp. 246-255, Jan. 2008.
- [6] G.K. Ottman, H.F. Hofmann, A.C. Bhatt, and G.A. Lesieutre, "Adaptive piezoelectric energy harvesting circuit for wireless remote power supply," *IEEE Transactions on Power Electronics*, vol. 17, no. 5, pp. 669-676, Sept. 2002.
- [7] D. Kwon and G.A. Rincón-Mora, "A rectifier-free piezoelectric energy harvester circuit," *Proc. IEEE International Symposium on Circuits and Systems (ISCAS)*, pp. 1085-1088, May 2009.
- [8] Y. Lam, W. Ki, and C. Tsui, "Integrated low-loss CMOS active rectifier for wirelessly powered devices," *IEEE Transactions on Circuits and Systems II, Express Briefs*, vol. 53, no. 12, pp.1378-1382, Dec. 2006.
- [9] T. Le, J. Han, A. von Jouanne, K. Mayaram, and T.S. Fiez, "Piezoelectric micro-power generation interface circuits," *IEEE J. Solid-State Circuits*, vol. 41, no. 6, pp. 1411-1420, June 2006.
- [10] N.J. Guilar, R. Amirtharajah, and P.J. Hurst, "A full-wave rectifier with integrated peak selection for multiple electrode piezoelectric energy harvesters," *IEEE J. Solid-State Circuits*, vol. 44, no.1, pp. 240-246, Jan. 2009.
- [11] Y.K. Ramadass and A.P. Chandrakasan, "An efficient piezoelectric energy-harvesting interface circuit using a bias-flip rectifier and shared inductor," *ISSCC Dig. Tech. Papers*, pp. 296-297, Feb. 2009.
- [12] A. Badel, D. Guyomar, E. Lefeuvre, and C. Richard, "Piezoelectric energy harvesting using a synchronized switch technique," *J. Intelligent Material Systems and Structures*, vol. 17, pp. 831-839, Aug./Sept. 2006.
- [13] D. Kwon and G.A. Rincón-Mora, "A single-inductor ac-dc piezoelectric energy-harvester/battery-charger IC converting  $\pm(0.35$  to 1.2V) to (2.7 to 4.5V)," *ISSCC Dig. Tech. Papers*, Feb. 2010.
- [14] S. Meninger, J. Mur-Miranda, R. Amirtharajah, A. Chandrakasan, and J. Lang, "Vibration-to-electric energy conversion," *IEEE Transactions on Very Large Scale Integration (VLSI) Systems*, vol. 9, no. 1, pp. 64-76, Feb. 2001.
- [15] E.O. Torres and G.A. Rincón-Mora, "Electrostatic energy-harvesting and battery-charging CMOS system prototype," *IEEE Transactions on Circuits and Systems I*, vol. 56, no. 9, pp. 1938-1948, Sept. 2009.
- [16] E.O. Torres and G.A. Rincón-Mora, "Energy budget and high-gain strategies for voltage-constrained electrostatic harvesters," *Proc. IEEE*

*International Symposium on Circuits and Systems (ISCAS)*, pp. 1101-1104, May 2009.